

Shortest Paths in Conservative Graphs

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Abstract

We give a polynomial algorithm to compute shortest paths in weighted undirected graphs with no negative cycles (conservative graphs). We show that our procedure gives a simple algorithm to compute optimal T -joins (and consequently all of their special cases, including weighted matchings). We finally give a direct algorithmic proof for arbitrary weights of a theorem of Sebő characterizing conservative graphs and optimal paths.

1 Conservative Graphs and T -joins

We propose an elementary and direct algorithm to find a shortest path between two nodes of an undirected graph with no cycle of negative weight. This shortest path problem can be formulated as an optimal degree-constrained subgraph problem and can therefore be solved by matching techniques, see e.g. [4]. Indeed, efficient algorithms for the minimum T -join problem (we define this concept later) had already been given by Edmonds and Johnson in [1].

Our main result is a purely combinatorial algorithm that finds a minimum weight T -join, giving a strongly polynomial algorithmic proof of a theorem of Sebö [9]. This theorem characterizes undirected graphs with no cycles of negative weight, in terms of potentials. An algorithmic proof of this theorem is given in [7], but that works only for unit weights. In Section 3, we provide an improved algorithm for unit weights, which is extended in Section 4 to a strongly polynomial algorithm for arbitrary rational weights.

We consider pairs (G, w) made up by an undirected multigraph $G = (V, E)$ with n nodes and m edges, together with a weight function $w = w(e)$, $e \in E$. G may have loops or parallel edges. The weight $w(F)$ of a set F of edges is $\sum_{e \in F} w(e)$. For $F \subseteq E$, let w_F be defined as $w_F(e) = -w(e)$ when $e \in F$ and $w_F(e) = w(e)$ when $e \in E \setminus F$. It is immediate to see that for $A, B \subseteq E$, we have that $w_A(B) = w(A \Delta B) - w(A)$.

Let T be an even subset of V . A T -join is a set of edges $J \subseteq E$ such that $d_J(v)$ is odd if and only if $v \in T$, where $d_J(v)$ is the degree of node v in the graph (V, J) . An *Eulerian subgraph* is an \emptyset -join. (Hence, an empty set of edges is an Eulerian subgraph). A T -join of minimum weight is said *w-optimal* (or *optimal*, when no confusion arises). Finally, (G, w) is *conservative* if it contains no cycle whose weight is negative (*negative cycle*). Mei Gu Guan [3] has given the following *coNP*-characterization of T -joins in terms of conservative graphs. (Note that this is not a *good characterization* in the sense of [5]).

Theorem 1.1 *A T -join J is optimal in (G, w) if and only if (G, w_J) is conservative.*

This follows by noting that the symmetric difference of two T -joins is an Eulerian subgraph, hence the union of a (possibly empty) set of disjoint cycles, and conversely the symmetric difference of a T -join and a cycle is again a T -join.

2 Clean and Switch

In (G, w) , fix a node $v_o \in V$. Assume given a $\{v_o, v\}$ -join $J_{v_o, v}$ for every $v \in V \setminus \{v_o\}$ plus the \emptyset -join $J_{v_o, v_o} = \emptyset$. Then $\mathcal{J}_{v_o} := \{J_{v_o, v} : v \in V\}$ is a *family of joins rooted at v_o* . A family \mathcal{J}_{v_o} is *w-optimal* if every $\{v_o, v\}$ -join in \mathcal{J}_{v_o} is *w-optimal*. Finally, \mathcal{J}_{v_o} is a *clean* family if every join in \mathcal{J}_{v_o} is acyclic. We now introduce two procedures, *Clean* and *Switch*.

Procedure *Clean* takes as input:

- A pair (G, w) and a family $\mathcal{J}_{v_o} = \{J_{v_o, v} : v \in V\}$.

Clean examines the joins in \mathcal{J}_{v_o} one by one. Every join $J_{v_o,v}$ in \mathcal{J}_{v_o} is decomposed as the disjoint union of an acyclic $\{v_o, v\}$ -join $J'_{v_o,v}$ and into a (possibly empty) set of cycles C_1, \dots, C_k .

If $w(C_i) < 0$ for some cycle C_i then *Clean* outputs C_i in (i) below.

Else $w(C_i) \geq 0$ for $1 \leq i \leq k$ and if $w(C_j) > 0$ for a cycle C_j in the set, then $w(J'_{v_o,v}) < w(J_{v_o,v})$ and *Clean* outputs $J'_{v_o,v}$ in (ii) below.

Otherwise $w(J'_{v_o,v}) = w(J_{v_o,v})$. If this is the case for all joins in \mathcal{J}_{v_o} , *Clean* outputs the clean family $\mathcal{J}'_{v_o} = \{J'_{v_o,v} : v \in V\}$ in (iii) below.

So the output is one of the following:

- (i) A cycle C such that $w(C) < 0$.
- (ii) An acyclic $\{v_o, v\}$ -join $J'_{v_o,v}$ such that $w(J'_{v_o,v}) < w(J_{v_o,v})$.
- (iii) A clean family $\mathcal{J}'_{v_o} = \{J'_{v_o,v} : v \in V\}$ with $w(J'_{v_o,v}) = w(J_{v_o,v}) \forall v \in V$.

Procedure *Switch* takes as input:

- A pair (G, w) , a family $\mathcal{J}_{v_o} = \{J_{v_o,v} : v \in V\}$ and a node $v'_o \in V \setminus \{v_o\}$.

The output is the following:

- The pair $(G, w_{J_{v_o,v'_o}})$ and the family $\mathcal{J}'_{v'_o} = \{J'_{v'_o,v} = J_{v_o,v} \Delta J_{v_o,v'_o} \forall v \in V\}$ rooted at v'_o .

Theorem 2.1 *Let $(G, w_{J_{v_o,v'_o}}, \mathcal{J}'_{v'_o})$ be the output of *Switch* when applied to $(G, w, \mathcal{J}_{v_o}, v'_o)$. Then (G, w) is conservative and \mathcal{J}_{v_o} is w -optimal if and only if $(G, w_{J_{v_o,v'_o}})$ is conservative and $\mathcal{J}'_{v'_o}$ is $w_{J_{v_o,v'_o}}$ -optimal.*

Proof: Assume (G, w) is conservative and \mathcal{J}_{v_o} is w -optimal. By Theorem 1.1, $(G, w_{J_{v_o,v'_o}})$ is conservative since $J_{v_o,v'_o} \in \mathcal{J}_{v_o}$ is w -optimal. Moreover, for every $J'_{v'_o,v} \in \mathcal{J}'_{v'_o}$ the pair $(G, (w_{J_{v_o,v'_o}})_{J'_{v'_o,v}}) = (G, w_{J_{v_o,v}})$ is conservative since $J_{v_o,v} \in \mathcal{J}_{v_o}$. So $\mathcal{J}'_{v'_o}$ is $w_{J_{v_o,v'_o}}$ -optimal.

Conversely, when *Switch* is applied to $(G, w_{J_{v_o,v'_o}}, \mathcal{J}'_{v'_o}, v_o)$, then the output is $(G, w, \mathcal{J}_{v_o})$. (Indeed, $J'_{v'_o,v_o} = J_{v_o,v_o} \Delta J_{v_o,v'_o} = J_{v_o,v'_o}$ for $J_{v_o,v_o} = \emptyset$.) \square

3 Unit pairs, bipartite pairs

If $w : E \mapsto \{-1, +1\}$ then (G, w) is a *unit* pair and we denote by E_+ the set of *positive* edges of weight +1 and by $E_- = E \setminus E_+$ the set of *negative* edges. We say (G, w) is a *bipartite pair* if every cycle of G has even weight. Note that a unit pair (G, w) is bipartite if and only if G is a bipartite loopless graph. In this case, (G, w) is a *bipartite unit* pair.

This section describes *Improve*, a polynomial algorithm which takes as input:

- A bipartite unit pair (G, w) and a clean family $\mathcal{J}_{v_o} = \{J_{v_o,v} : v \in V\}$.

The output of *Improve* is one of the following:

- (i) A check that (G, w) is conservative and \mathcal{J}_{v_o} is optimal.
- (ii) A negative cycle C of (G, w) .
- (iii) An acyclic $\{v_o, v\}$ -join $\tilde{\mathcal{J}}_{v_o, v}$ with $w(\tilde{\mathcal{J}}_{v_o, v}) < w(\mathcal{J}_{v_o, v})$.

Improve can be employed to test conservativeness of bipartite unit pairs or to find shortest paths in conservative bipartite unit pairs. *Improve* relies on three operations: *Clean*, *Switch* and *Contract*. Procedure *Contract* takes as input:

- A unit pair (G, w) and a clean family \mathcal{J}_{v_o} , where $w(\mathcal{J}_{v_o, v}) = w(v_o v) = +1$ for every neighbor v of v_o .

Contract obtains from G a new graph $G' = (V', E)$ by contracting the star $\delta(v_o)$ into a new node v'_o . This introduces loops but E and w are left unaffected. *Contract* sets $\mathcal{J}_{v'_o, v'_o} = \emptyset$ and for every node $v \in V' \setminus \{v'_o\}$, $\mathcal{J}'_{v'_o, v}$ is obtained from $\mathcal{J}_{v_o, v}$ by removing the unique edge having v_o as endnode. (Uniqueness follows since \mathcal{J}_{v_o} is clean). So the output is the following:

- A unit pair (G', w) and a family $\mathcal{J}'_{v'_o}$ of joins rooted at v'_o .

Theorem 3.1 *Let $(G', w, \mathcal{J}'_{v'_o})$ be the output of Contract when applied to $(G, w, \mathcal{J}_{v_o})$. Then (G, w) is conservative and \mathcal{J}_{v_o} is optimal if and only if (G', w) is conservative and $\mathcal{J}'_{v'_o}$ is optimal.*

Proof: Let C be a negative cycle of (G, w) . By contracting all edges in $\delta(v_o)$, C becomes an Eulerian graph of negative weight since $\delta(v_o) \subseteq E_+$. So C is the disjoint union of cycles, at least one of them is negative and (G', w) is not conservative.

Let $\tilde{\mathcal{J}}_{v_o, v}$ be a join of (G, w) such that $w(\tilde{\mathcal{J}}_{v_o, v}) < w(\mathcal{J}_{v_o, v})$. If v is a neighbor of v_o then $w(\tilde{\mathcal{J}}_{v_o, v}) \leq 0$ since $w(\mathcal{J}_{v_o, v}) = 1$. Contracting $\delta(v_o)$, $\tilde{\mathcal{J}}_{v_o, v}$ becomes an Eulerian graph of negative weight since $\tilde{\mathcal{J}}_{v_o, v}$ has at least one edge incident at v_o . Again (G', w) is not conservative. Assume v is not a neighbor of v_o . Contracting $\delta(v_o)$, $\tilde{\mathcal{J}}_{v_o, v}$ becomes a $\{v'_o, v\}$ -join $\tilde{\mathcal{J}}'_{v'_o, v}$ with $w(\tilde{\mathcal{J}}'_{v'_o, v}) = w(\tilde{\mathcal{J}}_{v_o, v}) - 1 < w(\mathcal{J}_{v_o, v}) - 1 = w(\mathcal{J}'_{v'_o, v})$. So $\mathcal{J}'_{v'_o}$ is not optimal.

Conversely let C be a negative cycle in (G', w) . In (G, w) , either C is a negative cycle, or a $\{u, v\}$ -join, with u and v neighbors of v_o . In the second case $\tilde{\mathcal{J}}_{v_o, v} = \{v_o u\} \cup C$ is a $\{v_o, v\}$ -join of (G, w) with $w(\tilde{\mathcal{J}}_{v_o, v}) \leq 0 < 1 = w(\mathcal{J}_{v_o, v})$.

So we assume (G', w) to be conservative. Let $\tilde{\mathcal{J}}'_{v'_o, v}$ be a $\{v'_o, v\}$ -join with $w(\tilde{\mathcal{J}}'_{v'_o, v}) < w(\mathcal{J}'_{v'_o, v})$. We can assume $\tilde{\mathcal{J}}'_{v'_o, v}$ to be acyclic, hence $d_{\tilde{\mathcal{J}}'_{v'_o, v}}(v'_o) = 1$. So there exists a neighbor u of v_o such that $\tilde{\mathcal{J}}'_{v'_o, v}$ is a $\{u, v\}$ -join in G . Hence $\tilde{\mathcal{J}}_{v_o, v} = \tilde{\mathcal{J}}'_{v'_o, v} \cup \{v_o u\}$ is a $\{v_o, v\}$ -join in G and $w(\tilde{\mathcal{J}}_{v_o, v}) = w(\tilde{\mathcal{J}}'_{v'_o, v}) + 1 < w(\mathcal{J}'_{v'_o, v}) + 1 = w(\mathcal{J}_{v_o, v})$. \square

Improve starts the following Recursion with (G, w) and the clean family \mathcal{J}_{v_o} as input.

Recursion A bipartite unit pair (G^*, w^*) and a clean family of joins $\mathcal{J}_{v_o^*} = \{\mathcal{J}_{v_o^*, v} : v \in V(G^*)\}$ rooted at v_o^* are received as input.

If G^* contains a single node, stop: (G, w) is conservative and \mathcal{J}_{v_o} is optimal.

If $w^*(\mathcal{J}_{v_o^*, v'_o}) \leq -1$ for some neighbor v'_o of v_o^* , then apply *Switch* to $(G^*, w^*, \mathcal{J}_{v_o^*}, v'_o)$.

Otherwise $w^*(J_{v_o^*,v}) \geq 1$ for all neighbors v of v_o^* . If there exists an edge $v_o^*v \in \delta(v_o^*)$ such that $w^*(v_o^*v) < w^*(J_{v_o^*,v})$, define $\tilde{J}_{v_o^*,v} = \{v_o^*v\}$ and go to the Surface Step.

Otherwise $\delta(v_o^*) \subseteq E_+$ and $w^*(J_{v_o^*,v}) = 1$ for every neighbor v of v_o^* . Apply *Contract* to $(G^*, w^*, \mathcal{J}_{v_o^*})$.

The output $(G', w', \mathcal{J}_{v_o'})$ of either *Switch* or *Contract* is given to *Clean*. If *Clean* finds a negative cycle or an acyclic join $\tilde{J}_{v_o',v}$ such that $w'(\tilde{J}_{v_o',v}) < w'(J_{v_o',v})$, go to the Surface Step. Otherwise the clean family obtained and (G', w') are the input of the next Recursion.

Surface Step Let $(G, w) = (G_0, w_0), (G_1, w_1), \dots, (G_k, w_k)$ be the sequence of pairs computed by *Switch* or *Contract* in the applications of the Recursion, where in (G_k, w_k) a negative cycle or a join $\tilde{J}_{v_k,v}$ such that $w_k(\tilde{J}_{v_k,v}) < w_k(J_{v_k,v})$ has been found. With k applications of Theorems 2.1 and 3.1 (whose proofs are constructive) we can find a negative cycle in (G, w) or a join $\tilde{J}_{v_o,v}$ such that $w(\tilde{J}_{v_o,v}) < w(J_{v_o,v})$. If an “improved” join $\tilde{J}_{v_o,v}$ has been found, apply *Clean* one last time to obtain a negative cycle or an acyclic improved join.

Remark 3.2 *Since (G, w) is a bipartite unit pair, G is a bipartite loopless graph and this property is maintained by the above algorithm.*

Remark 3.3 *Since (G, w) is a bipartite unit pair, then $w(J_{v_o,v})$ is odd (hence distinct from 0) whenever v and v_o are neighbors. So the two cases $w(J_{v_o,v}) \leq -1$ for some neighbor v of v_o and $w(J_{v_o,v}) \geq 1$ for all neighbors v of v_o considered in the Recursion are exhaustive.*

Remark 3.4 *The polynomiality of Improve is straightforward: Each time we apply Switch, we reduce the number of negative edges. Each time we apply Contract, we reduce the number of nodes. In order for (G, w) to be conservative E_- has to be a forest. Therefore we can assume $|E_-| < n$ and so the number of calls to Switch or Contract is $\mathcal{O}(n)$.*

So, if (G, w) is a bipartite unit pair which is conservative and \mathcal{J}_{v_o} is a clean family of joins rooted at v_o , then, with $\mathcal{O}(n^2)$ calls to *Improve*, \mathcal{J}_{v_o} can be turned into a clean optimal family.

4 Finding Optimal T -joins

In this section, we show that a version of *Improve* for general weight functions can be used to compute an optimal T -join, and hence an optimal matching, in any pair (G, w) .

We first describe a strongly polynomial procedure, w -*Improve*, which takes as input:

- A pair (G, w) , where w is rational (hence integral). A clean family \mathcal{J}_{v_o} .

and whose output is one of the following:

- (i) A check that (G, w) is conservative and \mathcal{J}_{v_o} is optimal.
- (ii) A negative cycle C of (G, w) .
- (iii) An acyclic $\{v_o, v\}$ -join $\tilde{J}_{v_o,v}$ with $w(\tilde{J}_{v_o,v}) < w(J_{v_o,v})$.

w-Improve relies on *Clean*, *Switch* and *w-Contract*:

w-Contract takes as input:

- A pair (G, w) , where $w(e) \neq 0$ for every $e \in E$. A clean family \mathcal{J}_{v_o} such that $0 \leq w(J_{v_o, v}) \leq w(v_o v)$ for every $v_o v \in \delta(v_o)$.

Let $\bar{w} = \min_{v_o v \in \delta(v_o)} \left\{ \frac{w(J_{v_o, v}) + w(v_o v)}{2} \right\} = \frac{w(J_{v_o, \bar{v}}) + w(v_o \bar{v})}{2}$. Note that $\bar{w} > 0$ since $w(v_o \bar{v}) > 0$. Define $w'(e) = w(e)$ for every edge $e \notin \delta(v_o)$ and $w'(e) = w(e) - \bar{w}$ for every edge $e \in \delta(v_o)$. Obtain G' from G by contracting the edges e with $w'(e) = 0$. Note that loops may have been created. Let v'_o be the node of G' containing v_o . (i.e. $v_o = v'_o$ if no edge has been contracted). A family $\mathcal{J}'_{v'_o}$ of joins is obtained from \mathcal{J}_{v_o} by defining $J_{v'_o, v'_o} = \emptyset$, performing the above contraction in all the joins of \mathcal{J}_{v_o} and discarding all joins $J_{v_o, v}$ if $v_o v$ is contracted.

So the output is the following:

- A pair (G', w') , where $w'(e) \neq 0$ for every edge e of G' , and a family $\mathcal{J}'_{v'_o}$ of joins rooted at v'_o .

The proof of the following theorem is an immediate extension of the proof of Theorem 3.1 and is left to the reader.

Theorem 4.1 *Let $(G', w', \mathcal{J}'_{v'_o})$ be the output of *w-Contract* when applied to $(G, w, \mathcal{J}_{v_o})$. Then (G, w) is conservative and \mathcal{J}_{v_o} is optimal if and only if (G', w') is conservative and $\mathcal{J}'_{v'_o}$ is optimal.*

Remark 4.2 *If (G, w) is a bipartite pair, and v is a neighbor of v_o , then $w(v_o v)$ and $w(J_{v_o, v})$ have the same parity and hence \bar{w} is an integer.*

Algorithm *w-Improve* first contracts all edges of zero weight (this does not affect conservativeness nor optimality of joins) as to guarantee that $w(e) \neq 0 \forall e$. (Note that this property is maintained by *Clean*, *Switch* and *w-Contract*).

Then *w-Improve* starts the following *Recursion* with (G, w) and \mathcal{J}_{v_o} as input:

Recursion A pair (G^*, w^*) , where $w^*(e) \neq 0$ for every edge e of G^* , and a clean family $\mathcal{J}_{v_o^*} = \{J_{v_o^*, v} : v \in V(G^*)\}$ of joins rooted at v_o^* are received as input.

If G^* has only one node, and no loop of G^* has negative weight stop: (G, w) is conservative and \mathcal{J}_{v_o} is optimal. If some loop has negative weight, go to the Surface Step.

If $w^*(J_{v_o^*, v'_o}) < 0$ for some neighbor v'_o of v_o^* , then apply *Switch* to $(G^*, w^*, \mathcal{J}_{v_o^*}, v'_o)$.

Otherwise $w^*(J_{v_o^*, v}) \geq 0$ for all neighbors v of v_o^* . If there exists an edge $v_o^* v \in \delta(v_o^*)$ such that $w^*(v_o^* v) < w^*(J_{v_o^*, v})$, define $\tilde{J}_{v_o^*, v} = \{v_o^* v\}$ and go to the Surface Step.

Otherwise $0 \leq w^*(J_{v_o^*, v}) \leq w^*(v_o^* v)$ for all edges $v_o^* v \in \delta(v_o^*)$. Apply *w-Contract* to $(G^*, w^*, \mathcal{J}_{v_o^*})$.

The output $(G', w', \mathcal{J}'_{v'_o})$ of either *Switch* or *w-Contract* is given to *Clean*. If *Clean* finds a negative cycle or an acyclic join $\tilde{J}'_{v'_o, v}$ such that $w'(\tilde{J}'_{v'_o, v}) < w'(J'_{v'_o, v})$, go to the Surface Step. Otherwise the clean family obtained and (G', w') are the input of the next Recursion.

Surface Step Let $(G, w) = (G_0, w_0), (G_1, w_1), \dots, (G_k, w_k)$ be the sequence of pairs computed by *Switch* or *Contract* in the applications of the Recursion, where in (G_k, w_k) a negative cycle or a join $\tilde{J}_{v_k, v}$ such that $w_k(\tilde{J}_{v_k, v}) < w_k(J_{v_k, v})$ has been found. With k applications of Theorems 2.1 and 3.1 (whose proofs are constructive) we can find a negative cycle in (G, w) or a join $\tilde{J}_{v_o, v}$ such that $w(\tilde{J}_{v_o, v}) < w(J_{v_o, v})$. If $\tilde{J}_{v_o, v}$ has been found, apply *Clean* one last time.

Theorem 4.3 *Algorithm w -Improve calls w -Contract $\mathcal{O}(m)$ times and Switch $\mathcal{O}(mn)$ times.*

Proof: To apply *Switch* on $(G, w, \mathcal{J}_{v_o}, v'_o)$ we must have $w(J_{v_o, v'_o}) < 0$. But $w_{J_{v_o, v'_o}}(J'_{v'_o, v_o}) = -w(J_{v_o, v'_o}) > 0$ and moreover $w_{J_{v_o, v'_o}}(J'_{v'_o, v}) = w(J_{v_o, v}) - w(J_{v_o, v'_o}) > w(J_{v_o, v})$.

This means that once the root of our family leaves v_o by *Switching*, it can not reenter v_o if no *w-Contractions* is involved. Hence the number of *Switchings*, between two consecutive *w-Contractions*, is at most n .

An edge uv of G is said *monotone* for $(G, w, \mathcal{J}_{v_o})$ when $|w(uv)| = |w(J_{v_o, u}) - w(J_{v_o, v})|$. Note that if uv is monotone for $(G, w, \mathcal{J}_{v_o})$, then uv is monotone for any $(G, w', \mathcal{J}'_{v_o})$ obtained from $(G, w, \mathcal{J}_{v_o})$ by *Switching*. The same holds for *Cleaning* as long as this procedure returns a clean family as in (i). Assume now $(G', w', \mathcal{J}'_{v'_o})$ is obtained from $(G, w, \mathcal{J}_{v_o})$ by applying *w-Contract*. If $uv \in E(G') \setminus \delta(v'_o)$ is not monotone for $(G', w', \mathcal{J}'_{v'_o})$ then uv is not monotone for $(G, w, \mathcal{J}_{v_o})$. If $v'_o u \in \delta(v'_o)$ is not monotone for $(G', w', \mathcal{J}'_{v'_o})$ then $v_o u$ is not monotone for $(G, w, \mathcal{J}_{v_o})$. Moreover, if $v_o \bar{v}$ is monotone for $(G, w, \mathcal{J}_{v_o})$, then *w-Contract* contracts $v_o \bar{v}$ and so G' has less edges than G . Otherwise, if $v_o \bar{v}$ is not monotone for $(G, w, \mathcal{J}_{v_o})$, then $w'(v'_o \bar{v}) = w(v_o \bar{v}) - \bar{w} = \frac{w(v_o \bar{v}) - w(J_{v_o, \bar{v}})}{2} = \bar{w} - w(J_{v_o, \bar{v}}) = -w'(J_{v'_o, \bar{v}})$ and $v'_o \bar{v}$ is monotone for $(G', w', \mathcal{J}'_{v'_o})$. Thus *w-Contract* is applied $\mathcal{O}(m)$ times and therefore *Switch* is applied $\mathcal{O}(mn)$ times. \square

Schulz, Weismantel and Ziegler [6] show that if we can find in strongly polynomial time a "better" solution of a 0/1-integer program, then we can solve such a program in strongly polynomial time, provided an initial solution is available. So we can derive from *w-Improve* a strongly polynomial algorithm to compute optimal $\{u, v\}$ -joins in conservative pairs.

We now show that if we can find optimal $\{u, v\}$ -joins in conservative pairs then we can find optimal T -joins in any conservative pair:

Remark 4.4 *Let $T = \{u_1, v_1, \dots, u_k, v_k\}$, $k \geq 2$ be an even subset of nodes in a conservative pair (G, w) . For $i = 1, \dots, k$ let J_i be an optimal $\{u_i, v_i\}$ -join in the pair $(G, w_{J_1 \Delta \dots \Delta J_{i-1}})$ ($J_0 = \emptyset$). Then for $i = 1, \dots, k$ the pair $(G, w_{J_1 \Delta \dots \Delta J_i})$ is conservative. In particular $J = J_1 \Delta J_2 \dots \Delta J_k$ is an optimal T -join in (G, w) .*

To conclude, the following well known fact, see e.g. [5], shows that in computing an optimal T -join for a pair (G, w) , w can always be assumed non-negative, hence (G, w) conservative:

Given a set of edges $F \subseteq E$ we define $T^F = \{v \in V : d_F(v) \text{ is odd}\}$, i.e. T^F is the set of nodes such that F is a T^F -join.

Theorem 4.5 *Given a pair (G, w) let T be any even subset of V and F be any subset of E . Then a subset J of E is a w -optimal T -join if and only if $J\Delta F$ is a w_F -optimal $(T\Delta T^F)$ -join.*

Proof: Note first that J is a T -join if and only if $J\Delta F$ is a $(T\Delta T^F)$ -join. By Theorem 1.1 J is w -optimal if and only if $(G, w_J) = (G, (w_F)_{F\Delta J})$ is conservative. This happens if and only if $J\Delta F$ is w_F -optimal. \square

Corollary 4.6 *Given a pair (G, w) and an even subset T of V , let $E_- = \{e \in E : w(e) < 0\}$. If J is an optimal $(T\Delta T^{E_-})$ -join in (G, w_{E_-}) then $J\Delta E_-$ is an optimal T -join in (G, w) .*

Note that $w_{E_-} \geq 0$.

5 A Theorem of Sebő

In this section, we use algorithm *Improve* to prove a characterization, due to A. Sebő [9] and conjectured by A. Frank, of the bipartite unit pairs that are conservative. This theorem implies most structural theorems about optimal T -joins and packing of T -cuts, see for instance [9] and [2], such as Seymour's result on packing T -cuts in bipartite graphs [10] and Sebő's theorem on packing T -borders [8].

We begin by formalizing the inverse of *Contract*:

Decontract applies to a bipartite unit pair (G', w') in which a node v'_o has been distinguished as *root*. Let $\{\delta_1, \dots, \delta_k\}$ be any partition of $\delta(v'_o)$, where we allow for some of the classes $\delta_1, \dots, \delta_k$ to be empty. Let v_o, v_1, \dots, v_k be new nodes, not in G' . For $i = 1, \dots, k$ replace every edge $v'_o v \in \delta_i$ with an edge $v_i v$ of the same weight. Next remove v'_o . Finally for $i = 1, \dots, k$ add any number (at least one) of positive edges between nodes v_o and v_i and designate v_o as the new root.

A direct implication of algorithm *Improve* is the following:

Lemma 5.1 *The conservative bipartite unit pairs are precisely the bipartite unit pairs which can be obtained from a graph consisting of a single node (taken as the first root) and no edge through a sequence of Decontractions and Switchings on optimal acyclic $\{v'_o, v_o\}$ -joins (where v'_o is the root before and v_o will be the root after Switching is performed).*

By Theorem 3.1 the decontraction of a conservative bipartite unit pair (G', w') is a conservative bipartite unit pair (G, w) with no zero weight cycle going through v_o . Hence for every optimal $\{v_o, v\}$ -join $J_{v_o, v}$ in (G, w) , $d_{J_{v_o, v}}(v_o) \leq 1$. In particular if $v = v_o$ then $J_{v_o, v} = \emptyset$, if v is a neighbor of v_o , $J_{v_o, v}$ is obtained by adding an edge in $\delta(v_o)$ to a zero weight Eulerian subgraph of (G', w') and if $v \in V(G')$ then $J_{v_o, v}$ is obtained by adding an edge in $\delta(v_o)$ to an optimal $\{v'_o, v\}$ -join of (G', w') .

For a pair (G, w) the *distance function* λ centered at v_o is defined as:

$$\lambda(v) = \min\{w(J_{v_o, v}) : J_{v_o, v} \text{ is a } \{v_o, v\}\text{-join}\} \quad \forall v \in V$$

Let λ' be the distance function centered at v'_o in (G', w') . The above argument implies $\lambda(v_o) = 0$, $\lambda(v) = 1$ for every neighbor of v_o and $\lambda(v) = \lambda'(v) + 1$ for every other node.

For every integer i , let G^i be the subgraph of G induced by $V^i = \{v \in V : \lambda(v) \leq i\}$. Let $\mathcal{D} = \{D : D \text{ is the node set of a connected component of some } G^i\}$. After defining V'_i, G'_i and \mathcal{D}' analogously for (G', w') , note that:

$$\{\delta(D) : D \in \mathcal{D}\} = \delta(v_o) \cup \{\delta(D') : D' \in \mathcal{D}'\} \quad (1)$$

On the other hand, by the following remark, *Switching* does not affect \mathcal{D} .

Remark 5.2 *Let λ be the distance function centered at v_o in a conservative pair (G, w) , J_{v_o, v'_o} an w -optimal $\{v_o, v'_o\}$ -join and λ' the distance function centered at v'_o in $(G, w_{J_{v_o, v'_o}})$. Then for every v in V we have $\lambda'(v) = \lambda(v) - w(J_{v_o, v'_o})$.*

Proof: Let \mathcal{J}_{v_o} be an w -optimal family of joins rooted at v_o with $J_{v_o, v'_o} \in \mathcal{J}_{v_o}$. Theorem 2.1 implies the $w_{J_{v_o, v'_o}}$ -optimality for the family $\{J'_{v'_o, v} = J_{v_o, v'_o} \Delta J_{v_o, v} \mid J_{v_o, v} \in \mathcal{J}_{v_o}\}$. Thus $\lambda'(v) = w_{J_{v_o, v'_o}}(J'_{v'_o, v}) = w(J_{v_o, v}) - w(J_{v_o, v'_o}) = \lambda(v) - w(J_{v_o, v'_o})$. \square

For every $D \in \mathcal{D}$, let $\delta_{D, v} = 0$ when $v \in D$ and $\delta_{D, v} = 1$ when $v \notin D$. A. Sebő [9] proves the following good-characterization of conservativeness for bipartite unit pairs:

Theorem 5.3 *A bipartite unit pair (G, w) is conservative if and only if:*

$$|\delta(D) \cap E_-| = \delta_{D, v_o} \quad \forall D \in \mathcal{D} \quad (2)$$

And from it he derives a characterization for optimal $\{v_o, v\}$ -joins:

Theorem 5.4 *Let $J_{v_o, v}$ be a $\{v_o, v\}$ -join in a conservative bipartite unit pair (G, w) . Then $J_{v_o, v}$ is optimal if and only if:*

$$w(\delta(D) \cap J_{v_o, v}) = \delta_{D, v} - \delta_{D, v_o} \quad \forall D \in \mathcal{D} \quad (3)$$

Remark 5.5 *Condition (3) characterizes optimal $\{v_o, v_o\}$ -joins (i.e. zero-weight Eulerian subgraphs) in a conservative bipartite unit pair (G, w) .*

Proof of Theorems 5.3 and 5.4: We first prove the "only if" direction of both theorems. Properties (2) and (3) hold trivially when G consists of a single node.

By Lemma 5.1, we need to consider two cases:

Case 1: (G, w) is obtained from a conservative bipartite unit pair (G', w') , for which both (2) and (3) hold, by *Decontracting*. Then $\delta(v_o) \subseteq E_+$ and consequently (1) implies that (2) holds for (G, w) since it holds for (G', w') . Let $J_{v_o, v}$ be an optimal $\{v_o, v\}$ -join in (G, w) . If $v = v_o$ then $J_{v_o, v} = \emptyset$ and (3) holds trivially. If v is a neighbor of v_o then $J_{v_o, v}$ is obtained by adding an edge in $\delta(v_o)$ to a zero weight Eulerian subgraph of (G', w') . If $v \in V(G')$ then $J_{v_o, v}$ is obtained by adding an edge in $\delta(v_o)$ to an optimal $\{v'_o, v\}$ -join of (G', w') . In both cases (3) holds for $\overline{D} = \{v_o\}$, since $v_o \in \overline{D}$ but $v \notin \overline{D}$ and consequently (1) implies that (3) holds for every $D \in \mathcal{D}$ since it holds for every $D \in \mathcal{D}'$ by induction.

Case 2: (G, w) is obtained from $(G, w_{J'_{v'_o, v_o}})$ by *Switching* on the $w_{J'_{v'_o, v_o}}$ -optimal join $J'_{v'_o, v_o}$, where $(G, w_{J'_{v'_o, v_o}})$ satisfies (2) and (3). In $(G, w_{J'_{v'_o, v_o}})$, let E'_+, E'_-, λ' and \mathcal{D}' as in accordance with the previous notation. By Remark 5.2 $\mathcal{D} = \mathcal{D}'$. Thus for every $D \in \mathcal{D} = \mathcal{D}'$:

$$\begin{aligned} |\delta(D) \cap E_-| &= |\delta(D) \cap E'_-| + w_{J'_{v'_o, v_o}}(\delta(D) \cap J'_{v'_o, v_o}) = \\ &= \delta_{D, v'_o} + (\delta_{D, v_o} - \delta_{D, v'_o}) = \delta_{D, v_o}. \end{aligned}$$

And the necessity of Theorem 5.3 is proven.

Let $\bar{J}_{v_o, v}$ be any optimal $\{v_o, v\}$ -join in (G, w) . Theorem 1.1 implies that $\bar{J}'_{v'_o, v} = \bar{J}_{v_o, v} \Delta J'_{v'_o, v_o}$ is a $w_{J'_{v'_o, v_o}}$ -optimal $\{v'_o, v\}$ -join. Thus for every $D \in \mathcal{D} = \mathcal{D}'$, we have:

$$\begin{aligned} w(\delta(D) \cap \bar{J}_{v_o, v}) &= \\ &= w_{\delta(D) \cap J'_{v'_o, v_o}}((\delta(D) \cap J'_{v'_o, v_o}) \Delta (\delta(D) \cap \bar{J}_{v_o, v})) - w_{\delta(D) \cap J'_{v'_o, v_o}}(\delta(D) \cap J'_{v'_o, v_o}) = \\ &= w_{J'_{v'_o, v_o}}(\delta(D) \cap \bar{J}'_{v'_o, v}) - w_{J'_{v'_o, v_o}}(\delta(D) \cap J'_{v'_o, v_o}) = \\ &= (\delta_{D, v} - \delta_{D, v'_o}) - (\delta_{D, v_o} - \delta_{D, v'_o}) = \delta_{D, v} - \delta_{D, v_o}. \end{aligned}$$

And the necessity of Theorem 5.4 is complete.

For the "if" part of both theorems observe first that for every edge $uv \in E$, we have $|\lambda(v) - \lambda(u)| = 1$ because u and v are on different sides of the bipartition of G . This means that $\{\delta(D) : D \in \mathcal{D}\}$ is a partition of E .

Let (G, w) be a pair satisfying (2) and C be any cycle in G . For every $D \in \mathcal{D}$, $|C \cap \delta(D)|$ is even and $|\delta(D) \cap E_-| \leq 1$, hence $|C \cap \delta(D) \cap E_-| \leq |C \cap \delta(D) \cap E_+|$. From this we obtain:

$$|C \cap E_-| = \sum_{D \in \mathcal{D}} |C \cap \delta(D) \cap E_-| \leq \sum_{D \in \mathcal{D}} |C \cap \delta(D) \cap E_+| = |C \cap E_+|$$

Thus (G, w) is conservative and the sufficiency of Theorem 5.3 follows.

Let $J_{v_o, v}$ be a $\{v_o, v\}$ -join satisfying (3) in a conservative bipartite unit pair (G, w) . Take an optimal $\{v_o, v\}$ -join $\bar{J}_{v_o, v}$. Since $\bar{J}_{v_o, v}$ satisfies (3) we have:

$$w(J_{v_o, v} \cap \delta(D)) = \delta_{D, v} - \delta_{D, v_o} = w(\bar{J}_{v_o, v} \cap \delta(D)) \quad \forall D \in \mathcal{D}$$

which implies $w(J_{v_o, v}) = w(\bar{J}_{v_o, v})$ since $\{\delta(D) : D \in \mathcal{D}\}$ is a partition of E . The sufficiency of Theorem 5.4 follows. \square

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